

## PRODUCT DATA SHEET

# 3DM-CV5-IMU: Inertial Measurement Unit

The 3DM-CV5 family of industrial-grade, board-level inertial sensors provides a wide range of triaxial inertial measurements, computed attitude, and navigation solutions.

In all models, the Inertial Measurement Unit (IMU) includes direct measurement of acceleration, angular rate, delta theta, and delta velocity. Compensation options include automatic compensation for magnetic anomalies, gyro and accelerometer noise, and noise effects. In models that include computed outputs, sensor measurements are processed through an auto-adaptive estimation filter algorithm to produce high accuracy computed outputs under dynamic conditions. The computed outputs vary between models and can include roll, pitch, and yaw. All sensors are fully temperature-compensated and calibrated over the operating temperature range. The use of Micro-Electro-Mechanical Systems (MEMS) technology allows for highly accurate, small, light-weight devices.

SensorConnect software is a user friendly program for device configuration. MIP Monitor (MicroStrain Inertial Protocol) can also be used. Both packages provide for device configuration, live data monitoring, and recording. Alternatively, the MIP Data Communications Protocol is available for development of custom interfaces and easy OEM integration.

The sensor operates independent of computer platform, operating system, or coding language.

## PRODUCT HIGHLIGHTS

- Triaxial accelerometer, gyroscope, and temperature sensors achieve the optimal combination of measurement qualities
- Smallest, lightest, highest performance IMU in its class



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## BEST IN CLASS PERFORMANCE

- Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- High-performance, low-drift gyros with low noise density and vibrational rectification error
- Direct PCB mount or chassis mount with ribbon cable
- Precision mounting alignment features

## EASE OF USE

- SensorConnect enables simple device configuration, live data monitoring, and recording
- Optional hardware communications-development kit available
- The MSCL API allows easy integration with C++, Python, .NET, C#, Visual Basic, LabVIEW and MATLAB environments
- MIP open byte level communication protocol

## COST EFFECTIVE

- Out-of-the-box solution reduces development time
- Volume pricing available

## APPLICATIONS

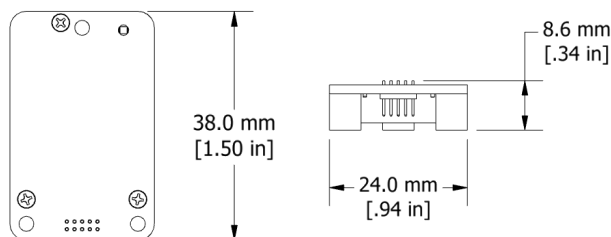
- Unmanned vehicle navigation
- Robotics
- Platform stabilization, artificial horizon
- Health and usage monitoring of vehicles

# MICROSTRAIN 3DM-CV5-IMU SPECIFICATIONS

General		
<b>Integrated Sensors</b>	Triaxial accelerometer, triaxial gyroscope, and temperature sensors	
<b>Data Outputs</b>	<b>Inertial Measurement Unit (IMU) outputs:</b> acceleration, angular rate, Delta-theta, Delta-velocity	
Inertial Measurement (IMU) Sensor Outputs		
	Accelerometer	Gyroscope
<b>Measurement Range</b>	±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g (optional)	±500°/sec (standard) ±250°, ±1000°/sec (optional)
<b>Non-linearity</b>	±0.04% fs	±0.06% fs
<b>Resolution</b>	0.05 mg (+/- 8 g)	<0.003°/sec (500 dps)
<b>Bias instability</b>	±0.08 mg	8°/hr
<b>Initial bias error</b>	±0.004 g	±0.01°/sec
<b>Scale factor stability</b>	±0.05%	±0.05%
<b>Noise density</b>	100 µg/√Hz (2 g)	0.0075°/sec/√Hz (500°/sec)
<b>Alignment error</b>	±0.05°	±0.08°
<b>Adjustable Bandwidth</b>	225 Hz (max)	500 Hz (max)
<b>Offset error over temperature</b>	0.02% (typ)	0.01% (typ)
<b>Gain error over temperature</b>	0.05% (typ) ±0.2% (max)	0.1% (typ) ±0.4% (max)
<b>Sampling rate</b>	1 kHz	1 kHz
<b>IMU Filtering</b>	First stage sigma delta Analog to Digital Converter sampled at 1 kHz. Second stage user adjustable digital low pass filter.	
<b>IMU data output rate</b>	1 Hz to 1000 Hz	

Operating Parameters	
<b>Communication</b>	TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default 115,200)
<b>Power source</b>	+3.2 to +5.2 V dc
<b>Power consumption</b>	360 mW (typ), 500 mW (max)
<b>Operating temperature</b>	-40°C to +85°C
<b>Mechanical shock limit</b>	500g/1ms absolute maximum survivability.*
<b>MTBF</b>	1,035,471 hours (Telcordia method gm/35C)
Physical Specifications	
<b>Dimensions</b>	38 mm x 24 mm x 9.7 mm
<b>Weight</b>	11 grams
<b>Enclosure material</b>	Aluminum
<b>Regulatory compliance</b>	CE, RoHS
Integration	
<b>Connectors</b>	Data/power output: Samtec FTSH Series. Connectivity board: Micro-D9
<b>Software</b>	SensorConnect and MIP Monitor software included; Windows XP/Vista/7/8/10 compatible
<b>Data Communications Protocol (DCP)</b>	Protocol compatibility across GX3, GX4, RQ1, GQ4, GX5, CX5 and CV5 product families
<b>Software development kit (SDK)</b>	MicroStrain Communication Library (MSCL) open source license includes full documentation and sample code.
<b>Hardware development kit</b>	Option purchased separately

\*Prolonged exposure to >2x full scale range can result in permanent damage. See manual for details



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